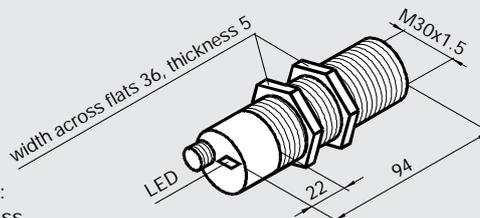


- Switch output
- 5 different output functions available
- Teaching input
- Can be synchronised
- Can be deactivated
- Watchdog



Figure 1
Housing material:
Nickel plated brass
Transducer material:
Epoxy resin/hollow glass sphere mixture
Polyurethane foam
Cover: PBT (Polybutylenterephthalate)



Synchronisation:

In order to suppress mutual interference, the sensor operates via one synchronised input. If the input is unswitched, the sensor operates at an internally generated pulse rate. The sensor can be synchronised by the super position of the square - shaped voltage. One synchronising pulse at the synchronisation input enables one measuring cycle to be completed. The pulse width must be greater than 100 µs. The measuring cycle commences with the descending flank. The state of the switching output changes after the switching threshold has been exceeded five times, as determined internally by five measurements. A low level ≥ 1 s, or an open synchronisation input results in normal operation of the sensor. Synchronisation cannot take place during teaching and vice versa.

Two operating modes are possible:

1. Multiple sensors are controlled with the same synchronising signal. The sensors operate on the same pulse.
2. The synchronising pulses are fed cyclically to only one sensor at a time. The sensors operate in multiplex mode. A high level at the synchronisation input deactivates the sensor.

To set the Switch Points:

The ultrasonic sensor is provided with a switching output with two teachable switch points. These are set up by applying the supply voltage -U_B bzw. +U_B to the teaching input. The supply voltage should be applied to the teaching input for at least 1 s. During the teaching process the LED's indicate whether the sensor has recognised the target. The switch points A1 and A2 are taught by voltage -U_B and + U_B, respectively.

Five functions can be set:

1. Window mode, normally open function
2. Window mode, normally closed function
3. One switch point, normally open function
4. One switch point, normally closed function
5. Detection of presence of object

Detection range:	60 mm ... 500 mm Figure 1
Version:	Transceiver with one switch output
Order code: pnp npn	UB 500-30GM-E2-V15 UB 500-30GM-E0-V15
Operating data: Detecting range Standart test plate (min. flat surface) Close range (unsuitable for switching) Aperture angle of sonic lobe Transducer frequency Response time Switching hysteresis Reproducibility Temperature drift Operating cycle frequency Measuring cycle time t _m Synchron. frequency equi-pulsed Synchron. frequency multiplex	60 mm ... 500 mm 100 mm x 100 mm 0 mm ... 60 mm approx. 5° at -3 dB approx. 375 kHz approx. 38 ms ≤ 1 % of the set operating distance ≤ 1 % 0.2 % / K max. 13 Hz approx. 6.5 ms ≤ 1 / t _{m1} ≤ 1 / t _{m1} + 1 / t _{m2} + ...
Electrical Data: Operating voltage U _B Ripple Rated operating current Switch output pnp npn Teaching input Synchronising input Synchronisation pulse width Synchronisation pause width Indicators: LED green LED red LED yellow	20 V DC ... 30 V DC ± 10 % _{ss} , U _B = 33 V ≤ 60 mA 200 mA (k), U _B -3 V short circuit/overload resistant E2 E0 -U _B ... (-U _B +2 V) near switch point (+U _B -2 V) ... +U _B far switch point -U _B ... (-U _B +1 V) Low level (-U _B +5 V) ... +U _B High level Input impedance 27 kΩ ≥ 100 µs ≥ 100 µs "Power on", teaching function object detected "Fault", object uncertain Switching condition indicator, teaching function, no object detected
Mechanical Data: Operating temperature range Storage temperature range Protection class to DIN 40 050 Permissible shock and vibration loading ⁵⁾ Connection type	248 Kelvin ... 343 Kelvin (-25 °C ... +70 °C) 233 Kelvin ... 358 Kelvin (-40 °C ... +85 °C) IP 65 b ≤ 30 g, T ≤ 11 ms f ≤ 55 Hz, a ≤ 1 mm Equipment connector - V15
in compliance with	EN 60974-5-2

5) to IEC 68-2-6 and IEC 68-2-27

Date of issue 05.06.1996

Ultrasonic Sensors Single Head System with one Switch Output

Teach window operation, normally open function:

- Set target at near switch point
- Teach switch point A1 with - U_B
- Set target at far switch point
- Teach switch point A2 with + U_B

Teach window operation, normally closed function:

- Set target at near switch point
- Teach switch point A2 with + U_B
- Set target at far switch point
- Teach switch point A1 with - U_B

Teach one switch point, normally open function:

- Set target at near switch point
- Teach switch point A2 with + U_B
- Cover sensor with the palm of the hand, or remove all objects from the detection range of the sensor
- Teach switch point A1 with - U_B

Teach one switch point, normally closed function:

- Set target at near switch point
- Teach switch point A1 with - U_B
- Cover sensor with the palm of the hand, or remove all objects from the detection range of the sensor
- Teach switch point A2 with + U_B

Teach detection of presence of object:

- Cover sensor with the palm of the hand, or remove all objects from the detection range of the sensor
- Teach switch point A1 - U_B
- Teach switch point A2 + U_B

Pre-setting of the switch points:

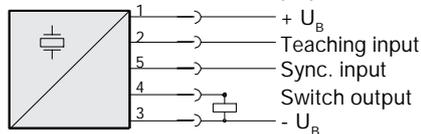
- A1: Near range
- A2: Nominal range

Note:

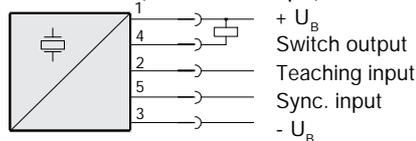
A programming Unit UB-PROG1 is obtainable for the basic setting of the switch points and output functions.

Standard symbol / Connections:

Transceiver (version E2, pnp)



Transceiver (version E0, npn)



V15 Connector arrangement



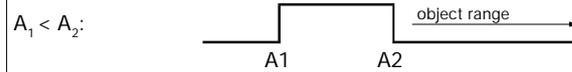
Accessories:

Cable connectors, see catalogue of inductive, capacitive and magnetic sensors and section 3.9 - Accessories.

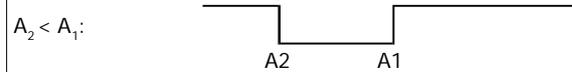
Operating condition - Indications	Green LED	Red LED	Yellow LED
Switch point teaching			
Object detected	flashing	off	off
No object detected	flashing	off	on
Object uncertain (teaching invalid)	off	flashing	off
Normal operation	on	off	switch condition
Interference (e.g. comp. air)	off	flashing	last condition

Programmed switching output function

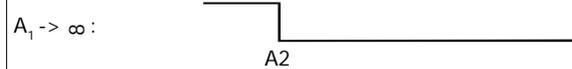
Window operation, normally open function



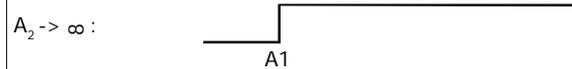
Window operation, normally closed function



One switch point, normally open function



One switch point, normally closed function



A₁ -> ∞, A₂ -> ∞ : Detection of presence of object

Object detected: Switch output closed
No object detected: Switch output open